

Solid-Fluid Interaction with Surface-Tension-Dominant Contact

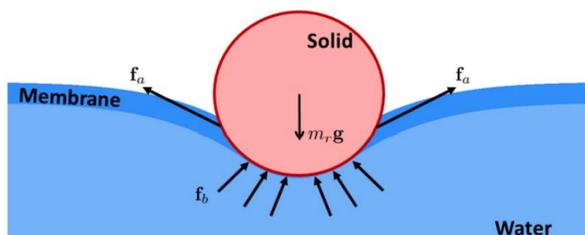
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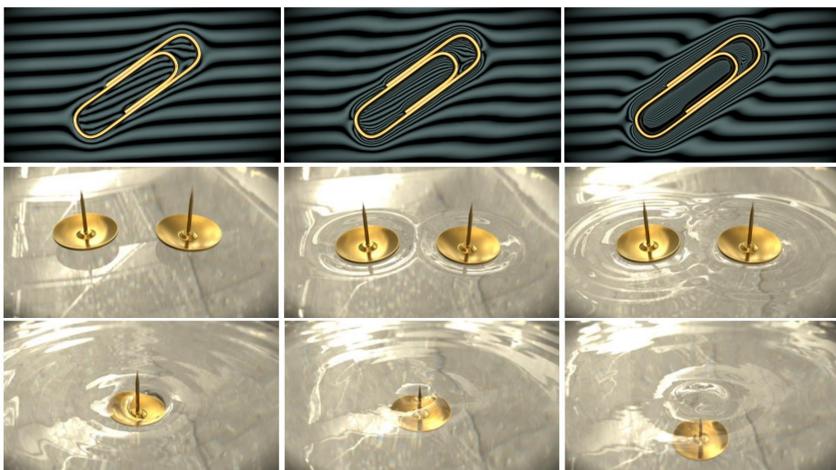
Introduction

Interactions between solids and fluids driven by the strong interfacial capillary forces are seen ubiquitously. From a computational perspective, accurately modeling the surface tension interacting with the gravity and the buoyancy requires proper treatment of three subsystems — the liquid, the solid, and the strongly-tensioned liquid interface between them.



The mainstream numerical paradigms of using an implicit level-set method to model the free-surface flow [Robinson-Mosher et al. 2008] suffer from **limitations** of accurately capturing the liquid-solid **contact perimeter** and fine-scale **capillary waves**. To tackle these computational challenges, we propose a novel “**three-way**” coupling mechanism by adding a **Lagrangian thin membrane** between the fluid and the solid.

Results



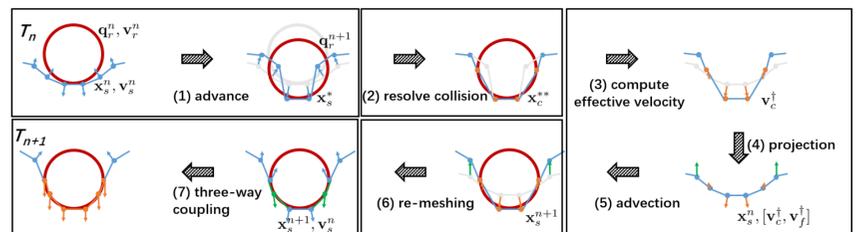
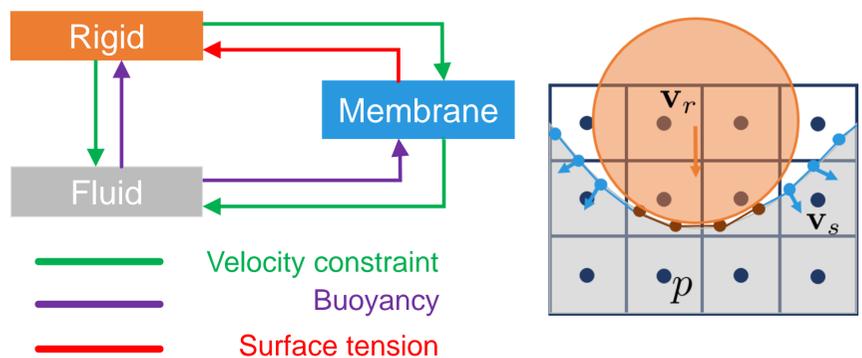
Discussion

We demonstrate the efficacy of our method through an array of rigid-fluid contact simulations dominated by strong surface tension, which enables the faithful modeling of a host of new surface-tension-dominant phenomena. But there are several limitations of our current method:

1. the three-way coupled system is **not symmetric positive definite**, which affects the solver’s performance when solving large-scale problems.
2. Our explicit mesh representation, though exhibiting outstanding performance on handling contact, **cannot handle the large topological evolution** of complex liquid surfaces efficiently.
3. Regarding the physical model, our current solver does **not support hydrophilic materials** and **contact angles** which limits its scope of applications.

Methods

$$\begin{bmatrix} \frac{V}{\rho} \mathbf{G}^T \mathbf{G} & -\mathbf{V} \mathbf{G}^T \mathbf{W} & -\mathbf{V} \mathbf{G}^T \mathbf{J}_r \\ -\mathbf{W}^T \mathbf{G} \mathbf{V} & -\mathbf{M}_s & -\mathbf{K}_{c,r} \Delta t^2 \\ -\mathbf{J}_r^T \mathbf{G} \mathbf{V} & -\mathbf{K}_{a,s} \Delta t^2 & -\mathbf{M}_r \end{bmatrix} \begin{bmatrix} \hat{\mathbf{p}} \\ \mathbf{v}_s^{n+1} \\ \mathbf{v}_r^{n+1} \end{bmatrix} = \begin{bmatrix} \mathbf{V} \mathbf{G}^T \mathbf{u}^* \\ -\mathbf{M}_s \mathbf{v}_s^n - \hat{\mathbf{f}}_c \Delta t - \mathbf{W}^T \mathbf{M} \mathbf{u}^* \\ -\mathbf{M}_r \mathbf{v}_r^n - \hat{\mathbf{f}}_a \Delta t - \hat{\mathbf{f}}_r \Delta t - \mathbf{J}_r^T \mathbf{M} \mathbf{u}^* \end{bmatrix}$$



Conclusion

We develop a novel numerical method to simulate surface-tension-dominant solid-fluid coupling:

1. In stead of using level set, we use a **Lagrangian membrane** to represent the fluid surface and discretize surface tension on it.
2. We then involve the membrane into the fluid-rigid system, constructing a **three-way coupling system**.
3. At last we design a **prediction-correction time scheme** to handle the collision between the membrane and the rigid.

Reference

[Robinson-Mosher et al. 2008] Avi Robinson-Mosher, Tamar Shinar, Jon Gretarsson, Jonathan Su, and Ronald Fedkiw. 2008. Two-way coupling of fluids to rigid and deformable solids and shells. ACM Trans. on Graphics 27, 3 (2008), 1–9.

